# **The Dining Philosophers**



**Operating Systems** Baochun Li University of Toronto

#### **We are going to discuss two problems**

- **These are classic thread synchronization problems**
- **They are examples to show how semaphores and monitors can be used to achieve synchronization —**
	- The Dining Philosophers Problem (Textbook 31.6) The Sleeping Barber Problem (not in the textbook, but in Lab 3)

## **The Dining Philosophers**

Baochun Li, Department of Electrical and Computer Engineering, University of Toronto

## **The Dining Philosophers Problem**

- **Five philosophers sit at a table**
- **One fork between two neighbouring philosophers**
- **Philosophers think, grab both forks, eat, put down both forks**
- **Models exclusive access to a limited number of resources (such as I/O devices) Each philosopher is**



```
while true do
   think()
   Pickup left fork
   Pickup right fork
   eat()
   Put down left fork
   Put down right fork
```
**modelled as a thread**

## **Is this a valid solution?**

```
philosopher(int i)
 while true do
   think()
   pickup_forks(i)
   eat()
   putdown_forks(i)
pickup_forks(int i)
   pickup_fork(i)
   pickup_fork((i+1) modulo 5)
putdown_forks(int i)
   putdown_fork(i)
   putdown_fork((i+1) modulo 5)
```
## **The Problem**

**It may happen that all five philosophers take their left fork at the same time, and then try to take their right fork, which is taken by a neighbouring philosopher!**

**No one is able to progress — a deadlock How do we solve this problem?**

## **Intuition: taking the left and right forks needs to be made into one atomic action**

## **Second Try: the Dining Philosophers Problem**

```
semaphore mutex = 1 // binary semaphore
philosopher(int i)
   while true do
     think()
     mutex.down()
     pickup_forks(i)
     eat()
     putdown_forks(i)
     mutex.up()
```
**Only one philosopher can be eating at a given time**

**But we should be able to allow two philosophers eating at the same time!** **First intuition:** define a smaller critical section by moving the binary semaphore operations into **pickup\_forks()** and **putdown\_forks()**

#### **Now the solution looks like this — correct?**

```
philosopher(int i)
 while true do
     think()
     pickup_forks(i)
     eat()
     putdown_forks(i)
pickup_forks(int i)
    mutex.down()
    pickup_fork(i)
    pickup_fork((i+1) modulo 5)
    mutex.up()
putdown_forks(int i)
     mutex.down()
     putdown_fork(i)
     putdown_fork((i+1) modulo 5)
     mutex.up()
```
**The solution looks fine for now, but we haven't implemented pickup\_fork() and putdown\_fork() yet!**

## **How do we implement pickup\_fork() and putdown\_fork()?**

We do not need to maintain any additional states to know if a fork is available

Just look at the status of two adjacent philosophers

- **They can be in one of the three states: eating, thinking, or "hungry" (waiting for forks to become available)**
- **A philosopher may only eat if both of his neighbours are not eating**
- **What if a philosopher tries to pickup a fork, but it is not available?**
	- It needs to wait for it to become available **thread synchronization**
	- His neighbour, once finished eating, will have to wake him up

#### **First try: synchronization with semaphores**

```
semaphore sem[5]= {5 of 0}
int status[5] = \{5 of THINKING}
pickup_forks(int i)
  mutex.down()
  status[i] = HUNGRYint left = (i+4) modulo 5, right = (i+1) modulo 5
  if status[left] == EATING or
      status[right] == EATING then
     sem[i].down()
  status[i] = EATINGmutex.up()
```
## **First try: synchronization with semaphores**

```
putdown_forks(int i)
   mutex.down()
  status[i] = THINKINGint left = (i+4) modulo 5, right = (i+1) modulo 5
   if status[left] == HUNGRY then
     sem[left].up()
   if status[right] == HUNGRY then
     sem[right].up()
   mutex.up()
```
**In pickup\_forks(), if a philosopher i has failed to pick up both forks, it calls sem[i].down(), which blocks itself, before calling mutex.up() to leave the critical section**

**No other thread is able to enter the critical section deadlock!**

**So how do we solve this problem?**

## **How about this solution?**

```
pickup_forks(int i)
   mutex.down()
  status[i] = HUNGRYint left = (i+4) modulo 5, right = (i+1) modulo 5
   if status[left] == EATING or 
      status[right] == EATING then
    mutex.up()
    sem[i].down()
   status[i] = EATING else
   status[i] = EATING mutex.up()
```
- **Philosopher 1 and 4 were both eating at this time**
- **They finish eating at the same time**
- **Philosopher 1 wakes up 2, and 4 wakes up 3, since both 2 and 3 are hungry at the time (2 waiting on sem[2], 3 on sem[3])**
- **Both sem[2].down() and sem[3].down() are allowed to proceed!**

## **Changing if to while?**

**Can we solve the problem by changing if to while in pickup\_forks()?**

**while** status[left] == EATING **or** status[right] == EATING **do mutex.up() sem[i].down()**

 $status[i] = EATING$ 

## **Changing if to while?**

**Can we solve the problem by changing if to while in pickup\_forks()?**

**while** status[left] == EATING **or** status[right] == EATING **do mutex.up() sem[i].down()**

 $status[i] = EATING$ 

**No — we are testing status[left] and status[right] without acquiring mutual exclusion locks!**

## **Correct implementation of pickup\_forks()**

```
pickup_forks(int i)
     mutex.down()
    status[i] = HUNGRYint left = (i+4) modulo 5, right = (i+1) modulo 5
    while status[left] == EATING or
           status[right] == EATING do
       mutex.up()
       sem[i].down()
       mutex.down()
    status[i] = EATINGmutex.up()
```
## **Alternative solution: revise putdown\_forks()**

## **Alternatively, we can leave pickup\_forks() as it was Instead, we revise putdown\_forks() —**

When a philosopher finishes eating, it **only** wakes up a neighbouring philosopher if it is sure that its other neighbour is not eating!

If it does wake up a neighbour, it sets its status to EATING

## **Alternative solution: revise putdown\_forks()**

```
pickup_forks(int i)
     mutex.down()
    status[i] = HUNGRYint left = (i+4) modulo 5, right = (i+1) modulo 5
```

```
 if status[left] == EATING or
    status[right] == EATING then
   mutex.up()
   sem[i].down()
else
```

```
status[i] = EATING mutex.up()
```
## **Alternative solution: revise putdown\_forks()**

```
putdown_forks(int i)
     mutex.down()
   status[i] = THINKINGint left = (i+4) modulo 5, right = (i+1) modulo 5
```

```
if status[left] == HUNGRY and
    status[(left+4) modulo 5] != EATING then
   status[left] = EATING
   sem[left].up()
if status[right] == HUNGRY and
    status[(right+1) modulo 5] != EATING then
   status[right] = EATING
   sem[right].up()
mutex.up()
```
**Using semaphores, even when solving a simple synchronization problem, is a bit too tricky**

**Task 1 in Lab 3 asks you to implement the Dining Philosophers problem using monitors and condition variables**

The monitor implementation in BLITZ follows MESA semantics

Keep this in mind when designing your solution

# **But semaphores are more powerful primitives — it allows us to design a simpler solution**

Baochun Li, Department of Electrical and Computer Engineering, University of Toronto

```
philosopher(int i)
 while true do
   think()
   pickup_forks(i)
   eat()
   putdown_forks(i)
pickup_forks(int i)
   pickup_fork(i)
   pickup_fork((i+1) modulo 5)
putdown_forks(int i)
   putdown_fork(i)
   putdown_fork((i+1) modulo 5)
```
#### **Towards designing a simpler solution**

```
semaphore forks[5]= {5 of 1}
pickup_fork(int i)
  forks[i].down()
putdown_fork(int i)
 forks[i].up()
```
**But what about the deadlock?**

## **Making the solution deadlock-free**

```
pickup_forks(int i)
  if i == 4 then
     pickup_fork((i+1) modulo 5)
     pickup_fork(i)
   else
     pickup_fork(i)
     pickup_fork((i+1) modulo 5)
putdown_forks(int i)
```
putdown\_fork(i) putdown\_fork((i+1) modulo 5)

#### **What we've covered so far**

**Three Easy Pieces: Chapter 31.6**